

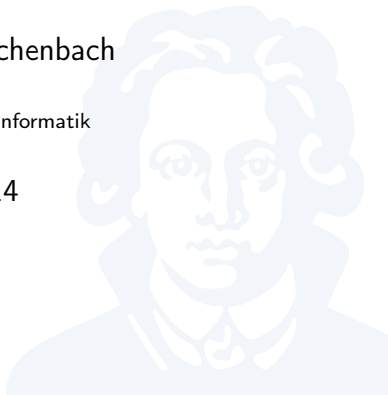
Foundations of Programming Languages

Implementing Iterative Control Structures

Prof. Dr. Christoph Reichenbach

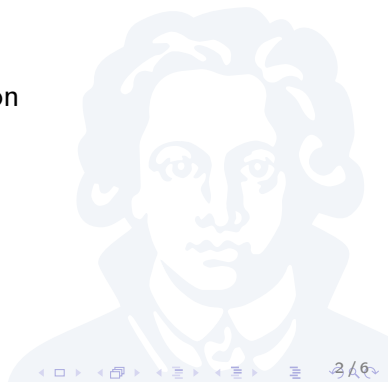
Fachbereich 12 / Institut für Informatik

29. Oktober 2014



Implementing Loops

- ▶ Compilers translate loops into:
 - ▶ tests
 - ▶ branches
- ▶ Some complications
- ▶ Some opportunities for optimisation

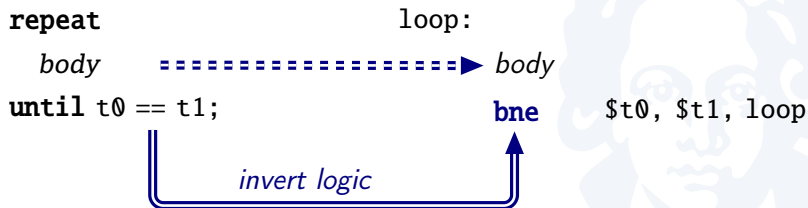


Logical Loops with Branches

```
repeat  
  body  
until t0 == t1;
```

Other implementation options exist

Logical Loops with Branches



Other implementation options exist

Logical Loops with Branches

```
while t0 == t1 do
    body
done
```

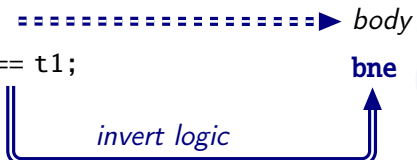
loop:

```
repeat
    body
until t0 == t1;
```

loop: *body*

bne \$t0, \$t1, loop

invert logic



Other implementation options exist

Logical Loops with Branches

```
while t0 == t1 do
    body
done
```

loop:
body

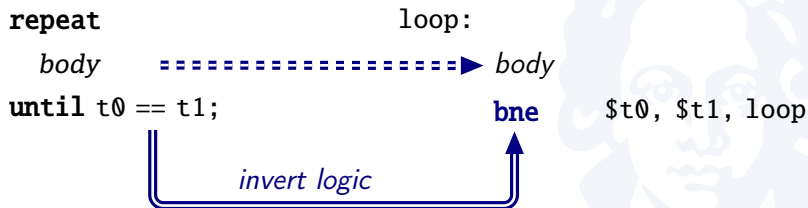
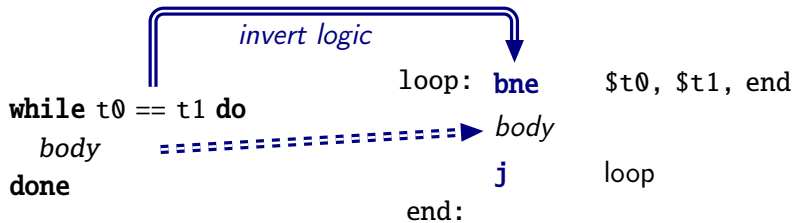
```
repeat
    body
until t0 == t1;
```

loop:
body
bne \$t0, \$t1, loop

invert logic

Other implementation options exist

Logical Loops with Branches

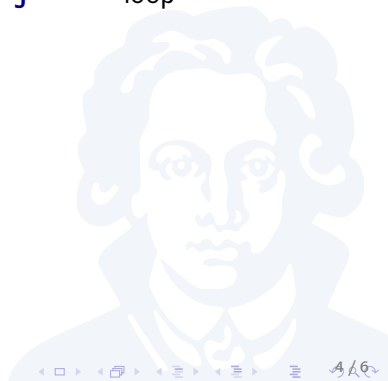


Other implementation options exist

Variable-Controlled Loops

```
for i := init to term      loop:  
do body .....⇒ body  
done;
```

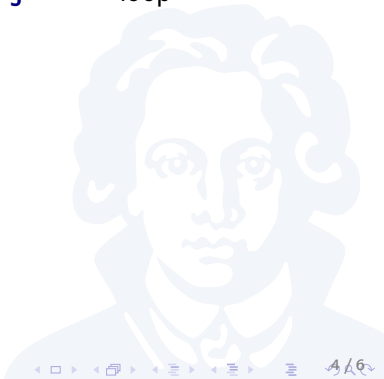
```
                                j      loop  
end:
```



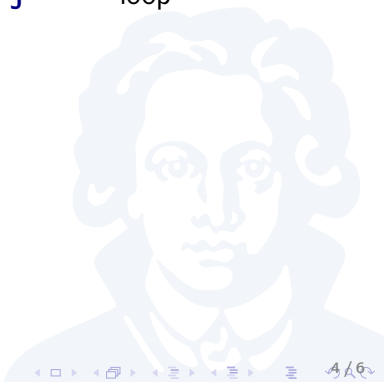
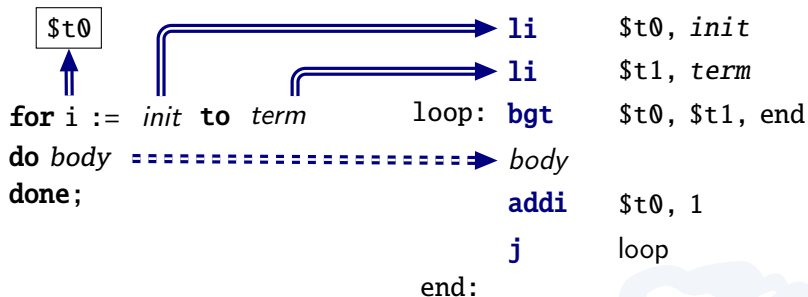
Variable-Controlled Loops

```
for i := init to term      loop:  
do body .....  
done;  
  
j      loop  
end:
```

\$t0, *init*
\$t1, *term*



Variable-Controlled Loops



Variable-Controlled Loops

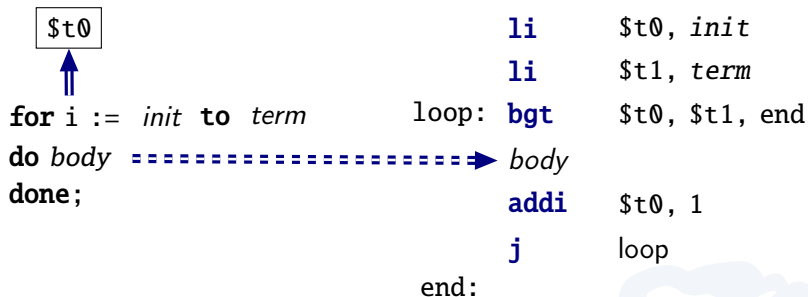
`$t0`

↑↑

```
for i := init to term
do body
done;
```

loop: `bgt $t0, $t1, end`
`body`
`addi $t0, 1`
`j loop`

end:



Variable-Controlled Loops

`$t0`

↑↑

```
for i := init to MAX_INT loop:
do body -----> body
done;
```

```
li    $t0, init
li    $t1, term
bgt   $t0, $t1, end
addi  $t0, 1
j     loop
end:
```

- ▶ `MAX_INT`: Maximum representable integer value

Variable-Controlled Loops

`$t0`

↑↑

```
for i := init to MAX_INT do body done;
```

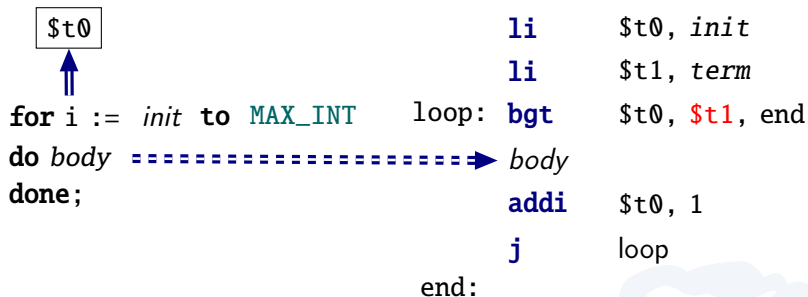
loop: `bgt $t0, $t1, end`

`body` → `body`

```
addi $t0, 1
j loop
end:
```

- ▶ `MAX_INT`: Maximum representable integer value
- ▶ `MAX_INT + 1`: *overflow* in last iteration

Variable-Controlled Loops



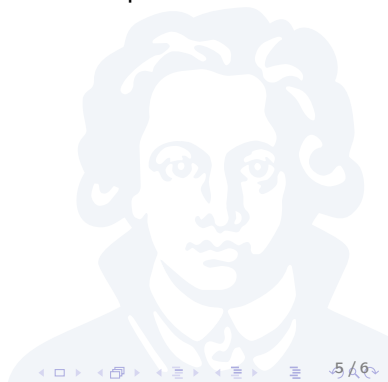
- ▶ *MAX_INT*: Maximum representable integer value
- ▶ *MAX_INT* + 1: *overflow* in last iteration
- ▶ If $\$t1 = \text{MAX_INT}$, branch is never taken

Unless we know that $\textit{term} < \text{MAX_INT}$, we need a different implementation strategy

Unrolling Loops: an Optimisation

```
for i := 1 to 5  
do s0 := s0 * i;  
done;
```

```
li    $t0, 1  
li    $t1, 5  
loop: bgt    $t0, $t1, end  
mul   $s0, t0  
addi  $t0, 1  
j     loop  
end:
```



Unrolling Loops: an Optimisation

```
for i := 1 to 5  
do s0 := s0 * i;  
done;
```

```
li    $t0, 1  
li    $t1, 5  
loop: bgt    $t0, $t1, end  
mul   $s0, t0  
addi  $t0, 1  
j     loop  
end:
```

```
muli  $s0, 1  
muli  $s0, 2  
muli  $s0, 3  
muli  $s0, 4  
muli  $s0, 5
```

Only feasible if initial, terminal values and step size known

Summary

- ▶ Post-test loops:
 - ▶ Single branch
- ▶ Pre-test loops:
 - ▶ Branch before body, additional jump operation
- ▶ Variable-controlled:
 - ▶ Branch before body, additional jump operation
 - ▶ Beware: completion check nontrivial with `MAX_INT`
- ▶ Loop unrolling:
 - ▶ Optimisation when initial/terminal loop values known